Recovering Behind-the-Meter Power Factor Control Settings

of Solar PV Inverters from Net Load Data

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1. Power Factor Control

Basic Description

The Problems We Are Solving

- Estimating Behind-the-Meter Power Factor Control Settings
 Filtering Net Load Data
 Power Factor Estimation
- 3. Making the Estimator More Robust
- 4. Summary and Results

Power Factor Control

- 1. Power factor control is the most common **reactive power control** method for inverter-based resources (IBRs).
- 2. A **unity power factor control setting** is the default of the IEEE 1547-2018 standard on the interconnection and interoperability of IBRs [1].

Graphical Depiction of Power Factor Control



Figure 1: Graphical description of inverter power factor control

Graphical Depiction of Power Factor Control



Figure 2: Real-time inverter power factor control action shot

Problem 1:

- 1. The power factor control settings of a *behind-the-meter* inverter **may be unknown or may change over time.**
- 2. This creates unobservable distribution network impacts.

Problem 2:

- 1. An engineer's **model** for a BTM IBR may be inaccurate.
- 2. It is often difficult to update this model.

Problem 3:

- Distribution engineers often only observe net load smart meter data at the BTM IBR interconnection, containing information about both the IBR generation and the user's demand,
- 2. It isn't obvious what the BTM power factor setting is.

The reactive power injection of an inverter with power factor control is determined by a line in the complex plane:

$$q_t^{pv} = \phi_{\Theta}(p_t^{pv}) = \frac{\Delta q}{\Delta p} p_t^{pv} \tag{1}$$

The slope of this line is the "sensitivity" of the IBR reactive power injections to real power injections.

Use trigonometry to relate the line slope to the power factor setting:

$$pf = cos(\phi_V - \phi_I) \implies pf = cos\left(atan2\left(\frac{\Delta q}{\Delta p}\right)\right),$$
 (2)

where ϕ_V, ϕ_I is the phase angle of the voltage and current, respectively.

Estimating Behind-the-Meter Power Factor Control Settings

Smart Meter Data

Distribution engineers often only have access to smart meter data:

$$\mathcal{D}_{l} = \{\mathbf{X}_{t}\}_{t=1}^{M} = \{(\mathbf{v}_{t}^{pcc}, p_{t}^{net}, q_{t}^{net})\}_{t=1}^{M},$$
(3)

where:

$$p_t^{net} = p_t^{pv} + p_t^{native}$$

$$q_t^{net} = q_t^{pv} + q_t^{native}$$
(4)

Note:

If we had a separate meter for the IBR, determining power factor control setting would be trivial.

Question:

From this **net load** data, can we determine the power factor control setting of the BTM inverter?

Lagging power factor settings:

$$\operatorname{\mathsf{atan2}}\left(\frac{\Delta q}{\Delta p}\right) < 0, \tag{5}$$

are typically used to prevent overvoltages from PV systems [4].

Hypothesis:

1. We can expose the behind-the-meter power factor control curve by taking the subset of the smart meter data that have " δ th percentile" extreme voltages:

$$\mathcal{D}_{l}^{\delta} = \{ \mathbf{X}_{t} \in \mathcal{D}_{l} : \mathbf{v}_{t}^{\text{pcc}} > \mathbf{V}_{\delta} \},$$
(6)

2. If the **voltage is high**, the local PV generation must be **high** and the load **low**, so the majority of the net measurement must be from PV.

Real Data: Non-Unity Power Factor Control



Figure 3: Non-unity power factor control: 99th percentile voltage filter

Real Data: Unity Power Factor Control



Figure 4: Unity power factor control: 99th percentile voltage filter

Perform ordinary least squares regression on the filtered active and reactive power time series vectors (\tilde{p} and \tilde{q}):

$$\hat{\Theta} = (\mathbf{A}^{\mathsf{T}}\mathbf{A})^{-1}\mathbf{A}^{\mathsf{T}}\tilde{\mathbf{q}}$$
(7)

where¹:

$$\Theta = \begin{bmatrix} \underline{\Delta q} & b \end{bmatrix}^{T}, \text{ and } \mathbf{A} = \begin{bmatrix} \vdots & \vdots \\ \tilde{\mathbf{p}} & 1 \\ \vdots & \vdots \end{bmatrix}.$$
(8)

We can now estimate the power factor from net load data.

¹Usually we have b = 0.

Power Factor Estimation

Use trigonometry to recover the power factor setting with the regression slope:

$$\hat{pf} = \cos\left(\operatorname{atan2}\left(\frac{\widehat{\Delta q}}{\Delta p}\right)\right),$$

where ϕ_V, ϕ_I is the phase angle of the voltage and current, respectively.

(9)

Making the Estimator More Robust

A common way to build robustness to noise is to solve:

$$\min_{\Theta} ||\mathbf{\tilde{q}} - \mathbf{A}\Theta||_1, \tag{10}$$

where the loss function in (10) is the sum of the absolute value of the residuals:

$$|\tilde{\mathbf{q}} - \mathbf{A}\Theta||_{\ell_1} = \sum_{t=1}^{M'} |\tilde{q}_t - a_t^T\Theta|.$$
(11)

Alternatively, trade off bias and variance with the Huber Loss Function [3, 2]:

$$l_{\epsilon} = \begin{cases} ||\tilde{\mathbf{q}} - \mathbf{A}\Theta||_{2}^{2} & ||\tilde{\mathbf{q}} - \mathbf{A}\Theta||_{2} \le \epsilon \\ \epsilon(||\tilde{\mathbf{q}} - \mathbf{A}\Theta||_{\ell_{1}} - \frac{1}{2}\epsilon) & \text{otherwise} \end{cases}$$
(12)

Summary and Results

Table 1: Performance evaluations (MAE) of power factor estimation for 50real BTM PV systems

PF Control Type	ℓ_1	Huber, $\epsilon = 7 imes 10^{-2}$
Unity	0.0000571	0.00343
Non-unity	0.0104	0.0103

Results:

We can estimate **unity and non unity** PF control settings from net load data with high accuracy.

Performance Summary



Figure 5: Scatter plot of estimated power factor vs. true power factor for all datasets studied

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